

PIC. 1

PIC. 2

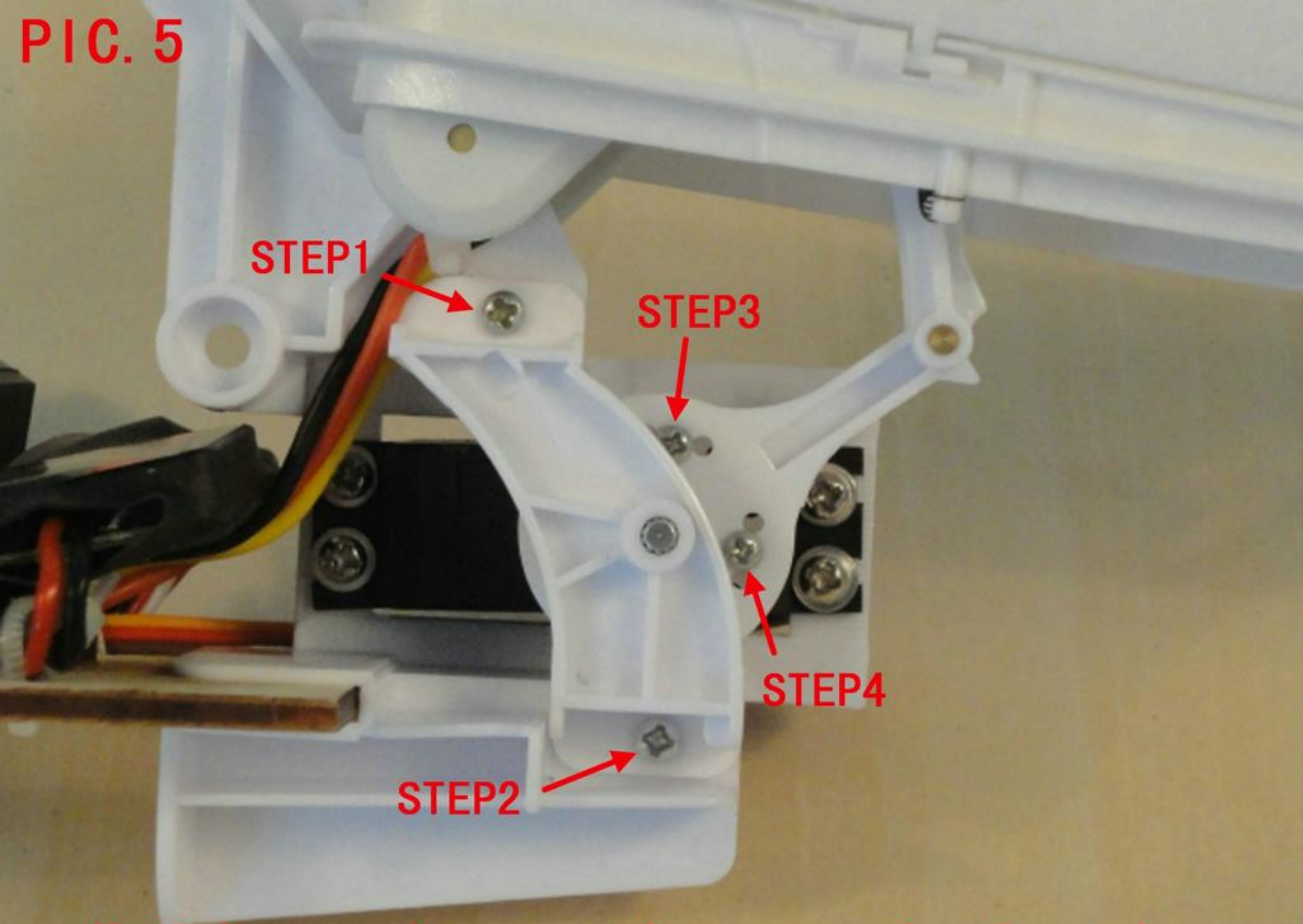




PIC. 3

PIC. 4





PIC. 5

STEP1

STEP3

STEP4

STEP2

Untighten and remove the screws in the order

PIC. 6



PIC. 7



PIC. 9



PIC. 10



Remove the locking servo screws



PIC. 11

Cut the wire and remove the servo

PIC. 12



The new servo

PIC. 13



The new servo

PIC. 14





PIC. 15

Switch on the transmitter, ensure that the throttle stick and its trim is at their min position

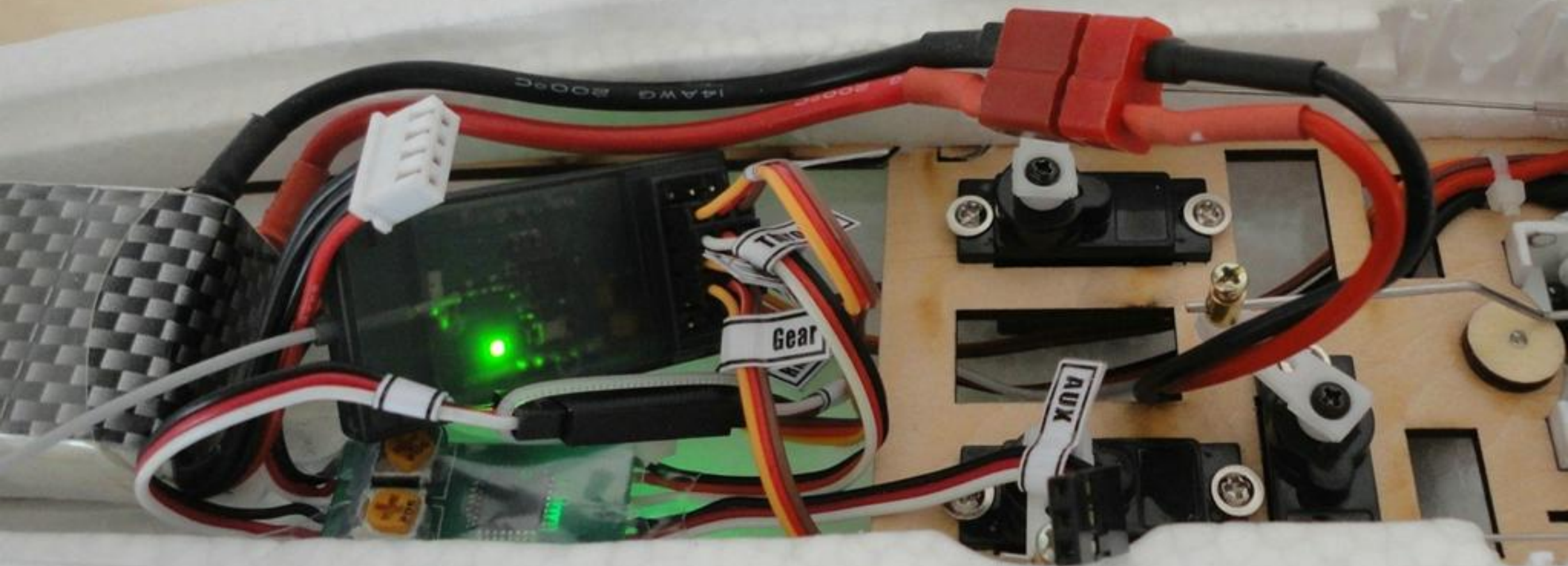
PIC. 16

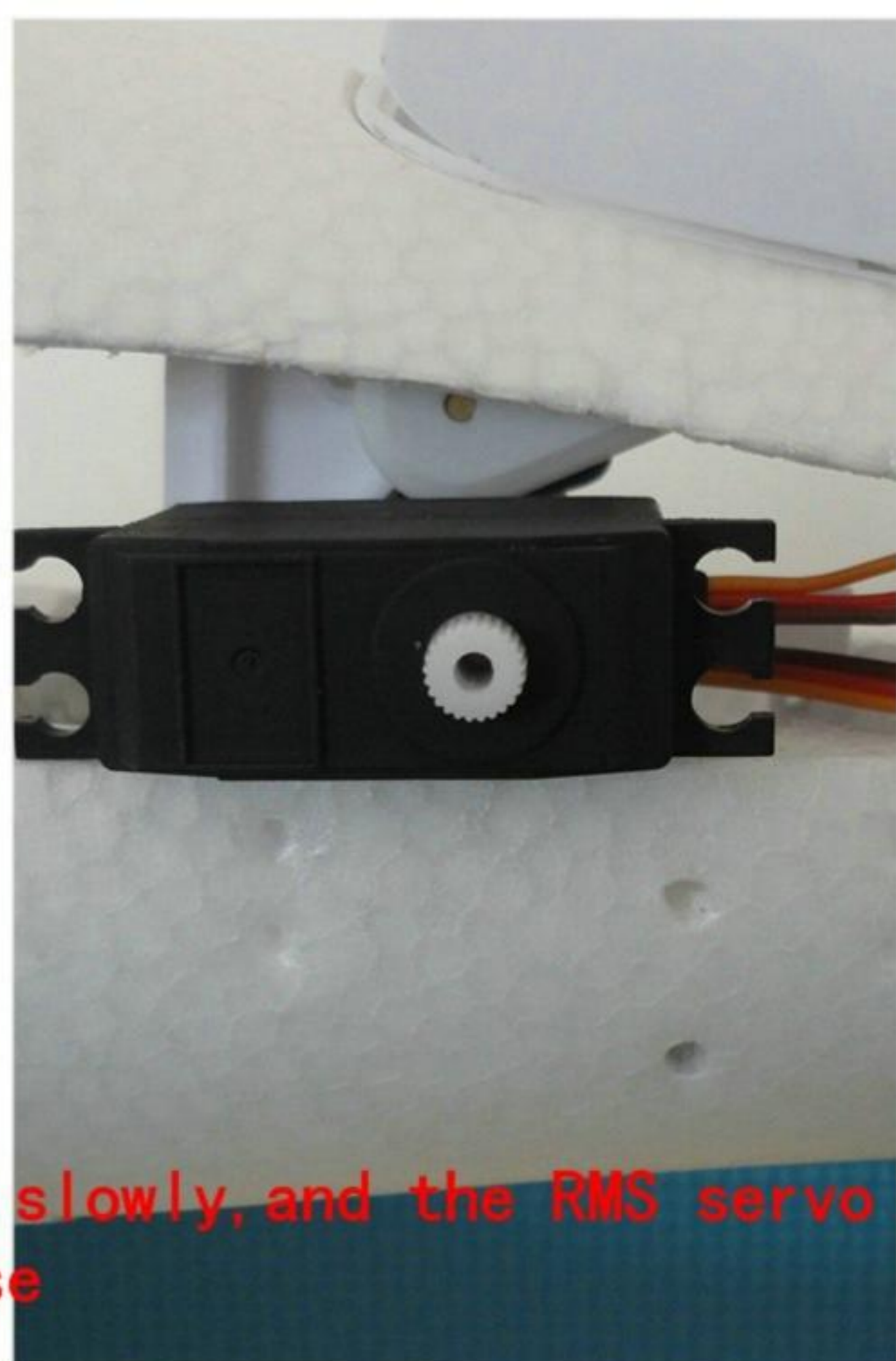
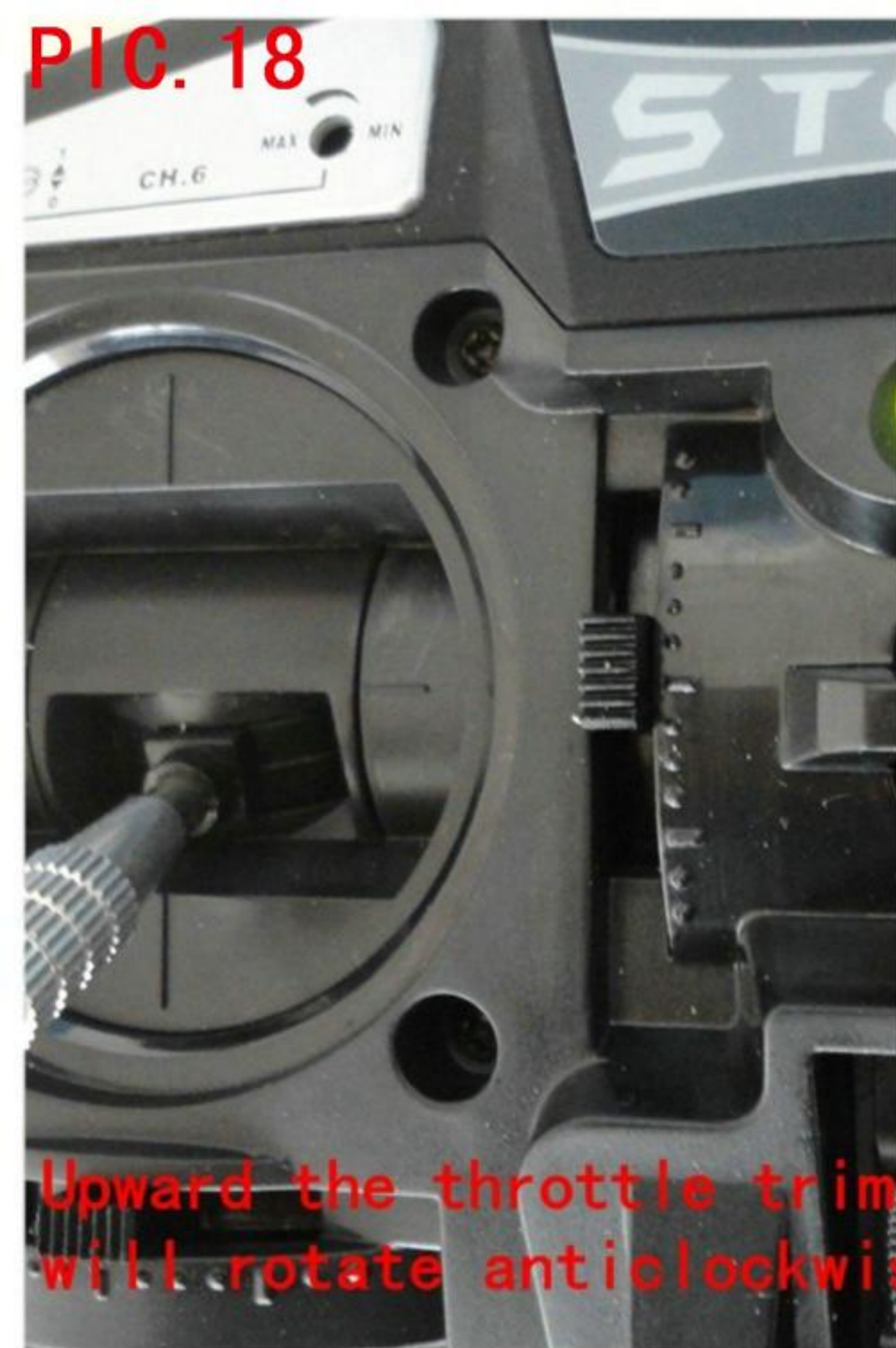


Set the low end point adjusters of RMS servo in their mid position

PIC. 17

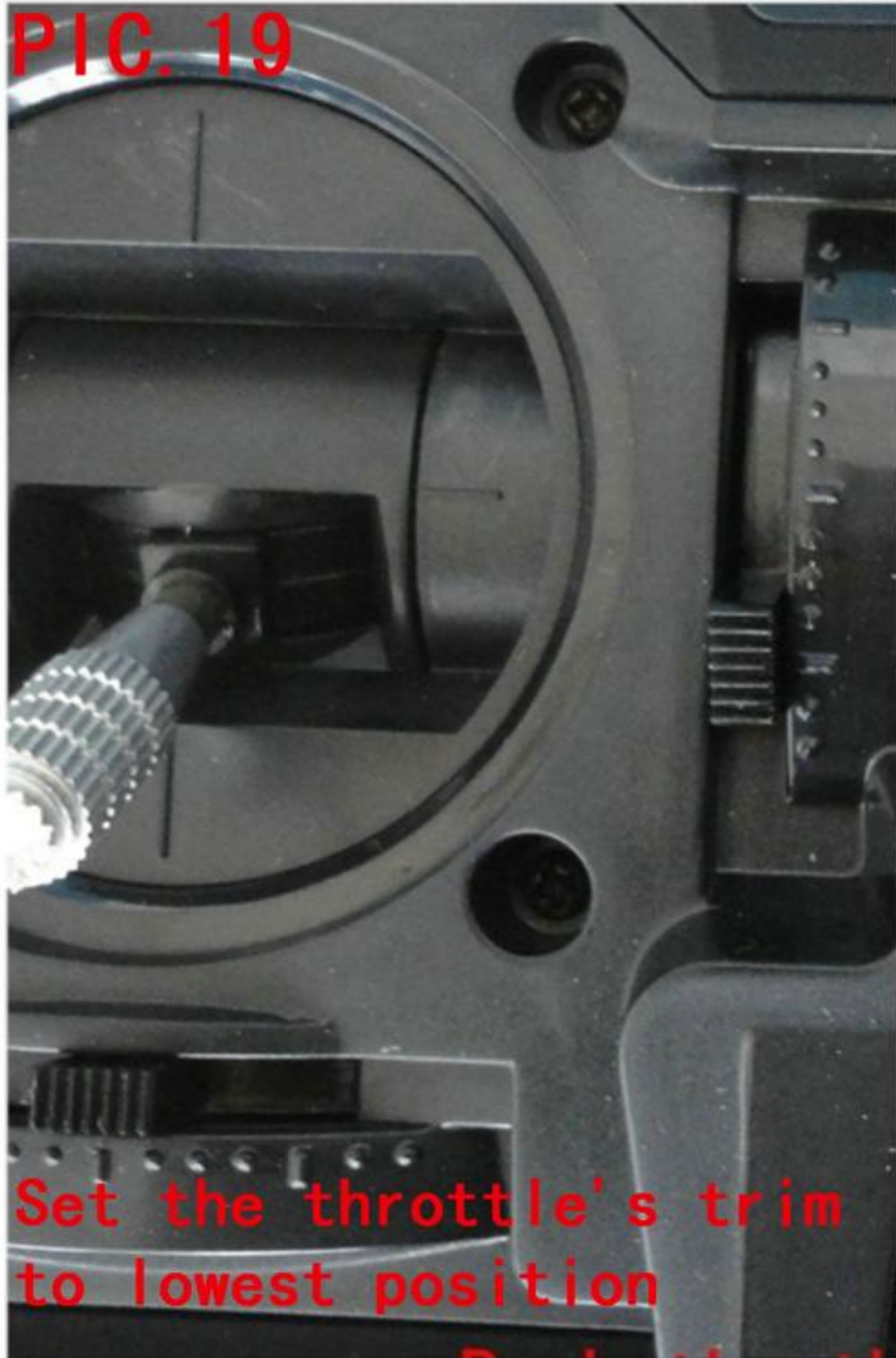
Power the plane



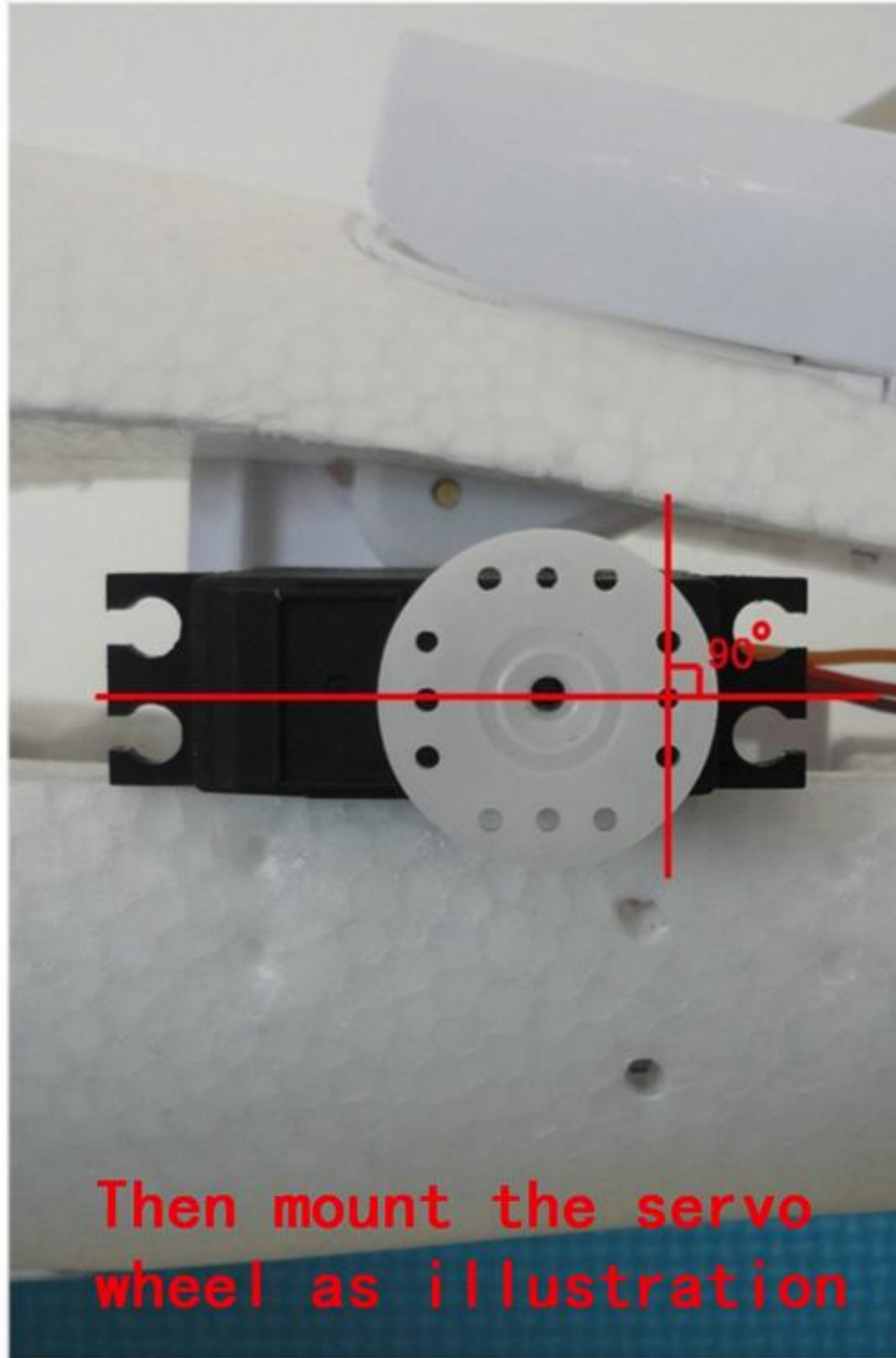


Upward the throttle trim slowly, and the RMS servo will rotate anticlockwise

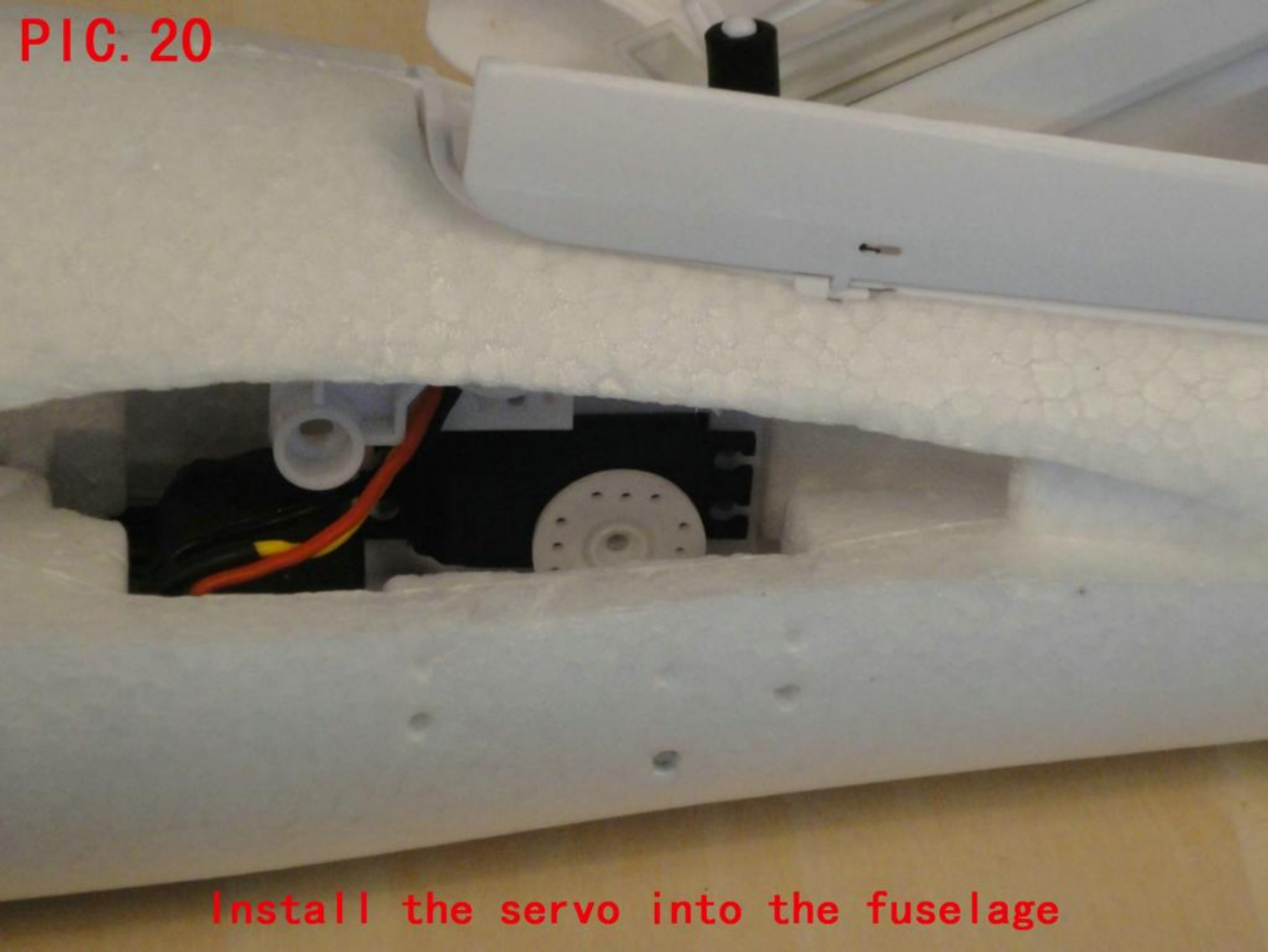
PIC. 19



Set the throttle's trim
to lowest position



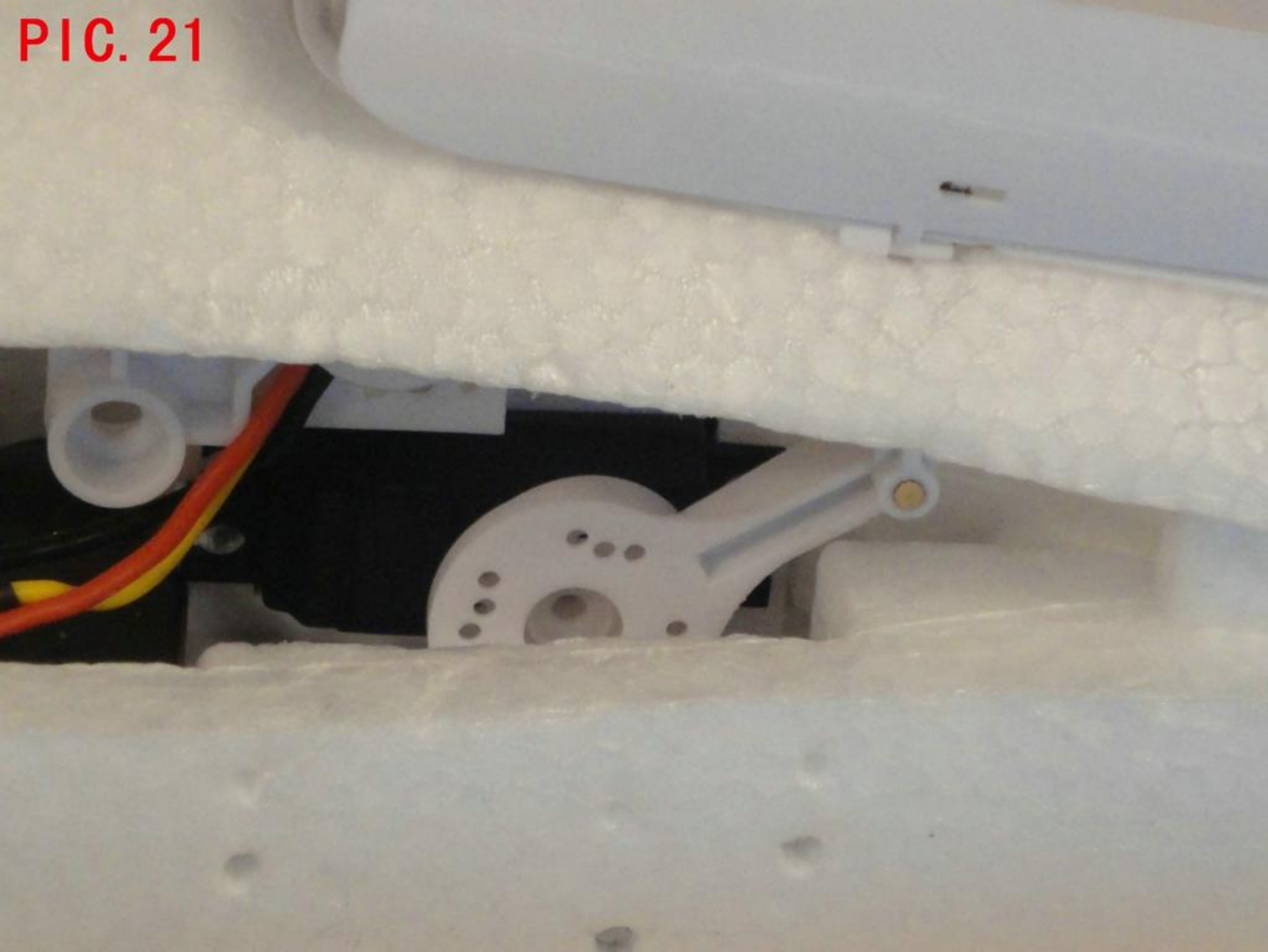
Then mount the servo
wheel as illustration



PIC. 20

Install the servo into the fuselage

PIC. 21



PIC. 22



Infix two tapping screws into the holes on the support, ensure the washer on the shaft not be lost

PIC. 23



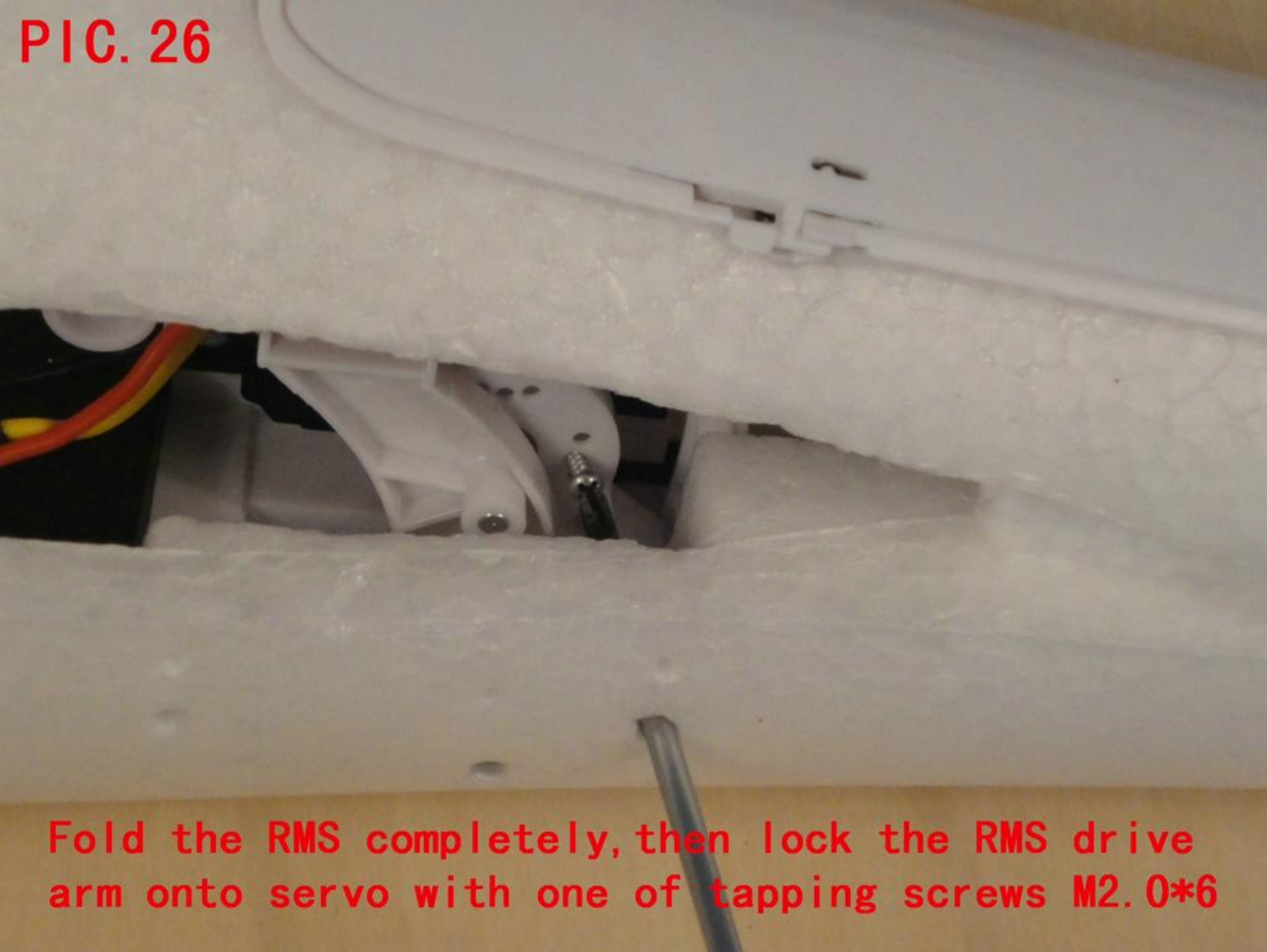


PIC. 24

Tighten the screws



PIC. 25



PIC. 26

Fold the RMS completely, then lock the RMS drive arm onto servo with one of tapping screws M2.0*6





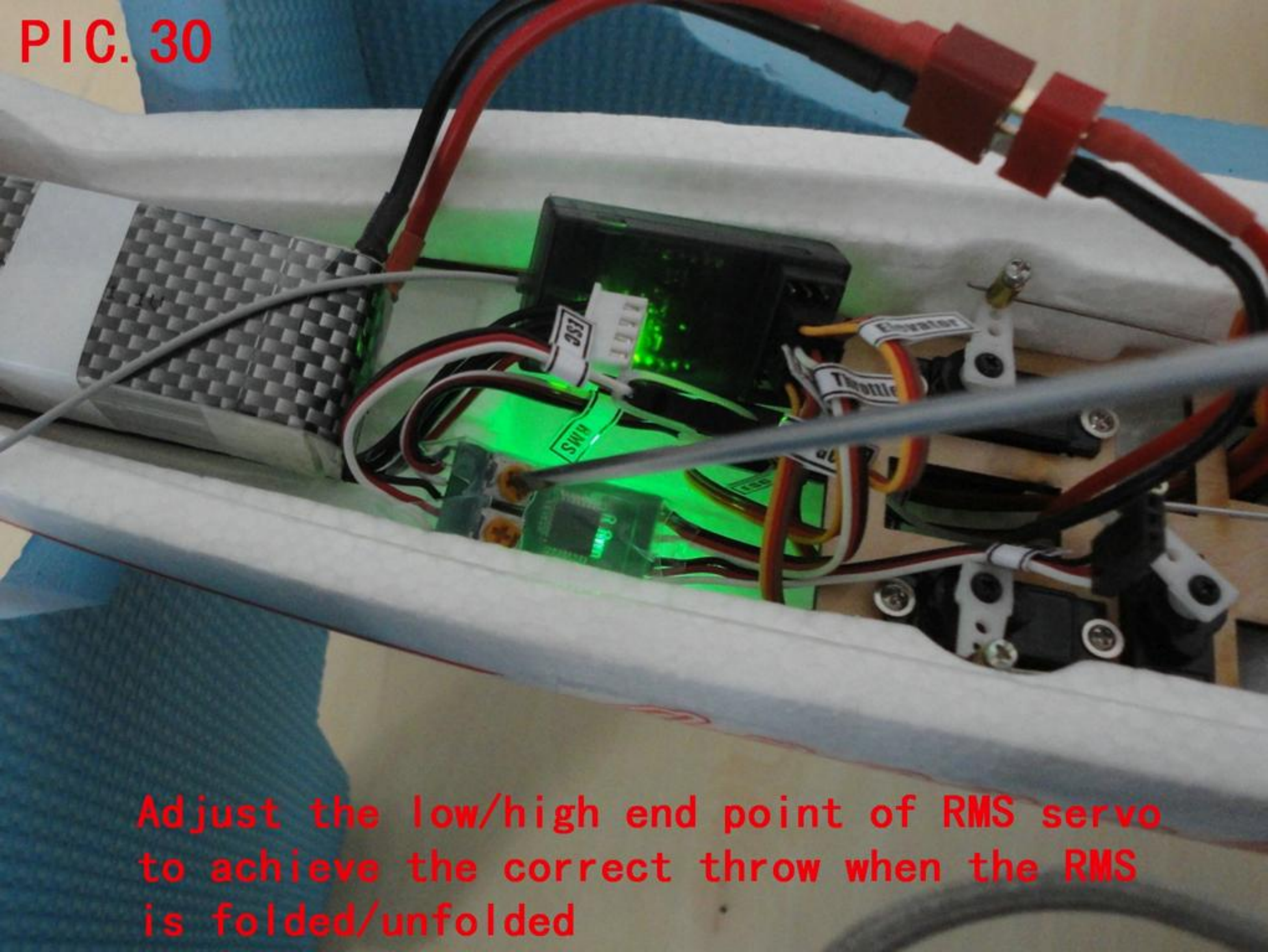
PIC. 28

Lock the servo into its position with screws



PIC. 29

PIC. 30



Adjust the low/high end point of RMS servo to achieve the correct throw when the RMS is folded/unfolded