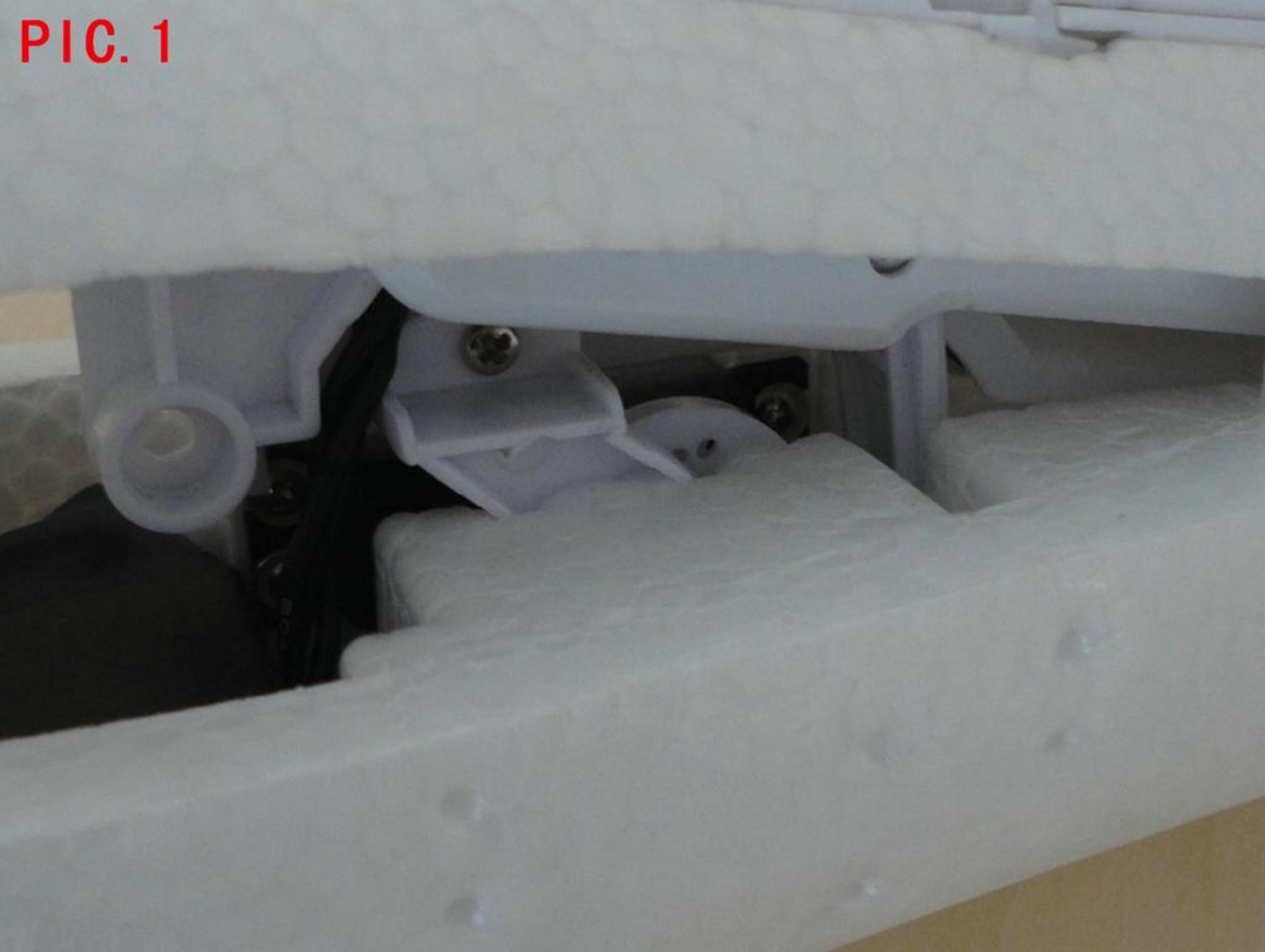


PIC. 1



PIC. 2



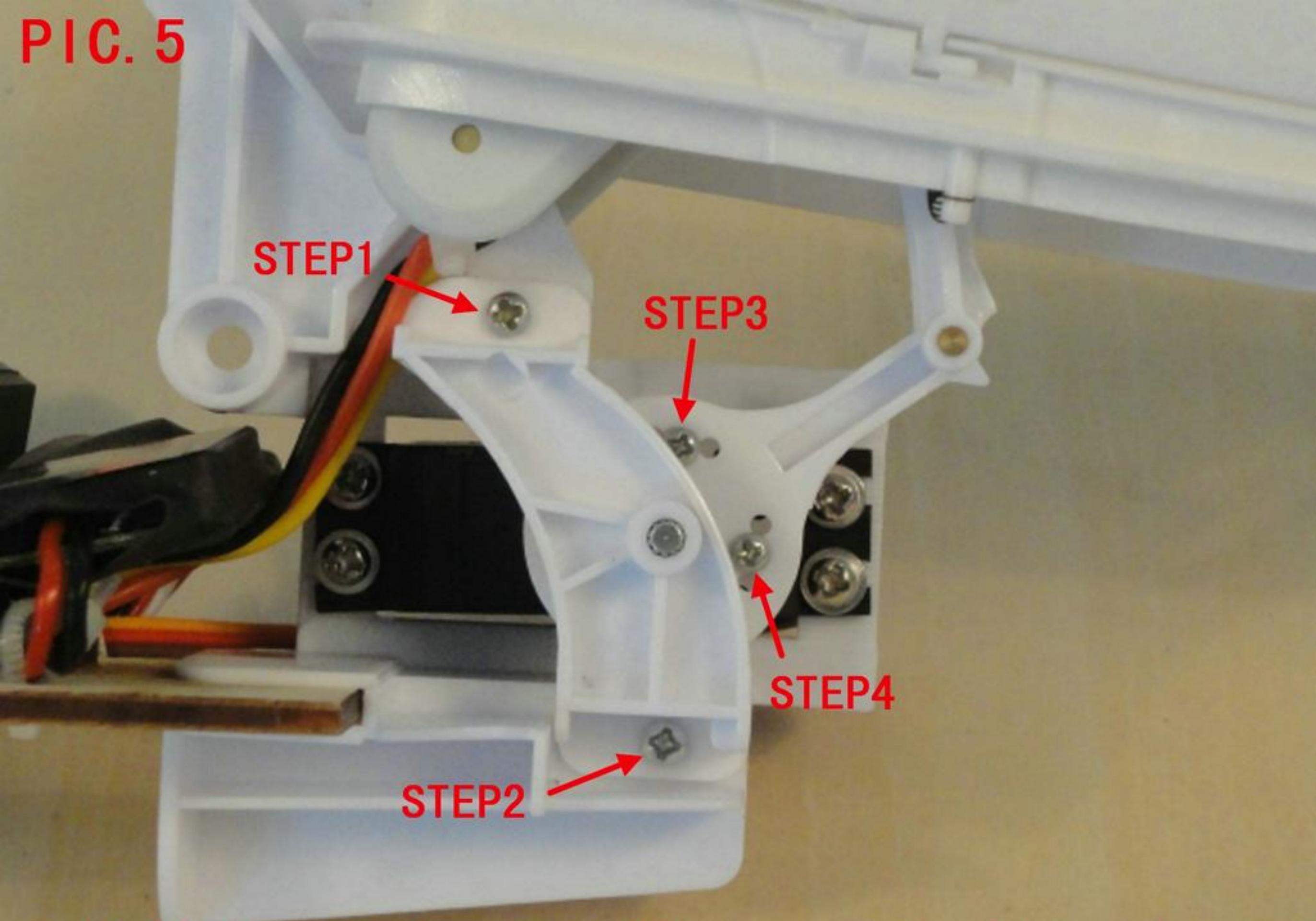
PIC. 3



PIC. 4



**PIC. 5**



**Untighten and remove the screws in the order**

PIC. 6



PIC. 7



PIC. 9



**PIC. 10**



**Remove the locking servo screws**



PIC. 11

Cut the wire and remove the servo

PIC. 12



The new servo

**PIC. 13**



**The new servo**

PIC. 14



PIC. 15

Switch on the transmitter, ensure that the throttle stick and its trim is at their min position



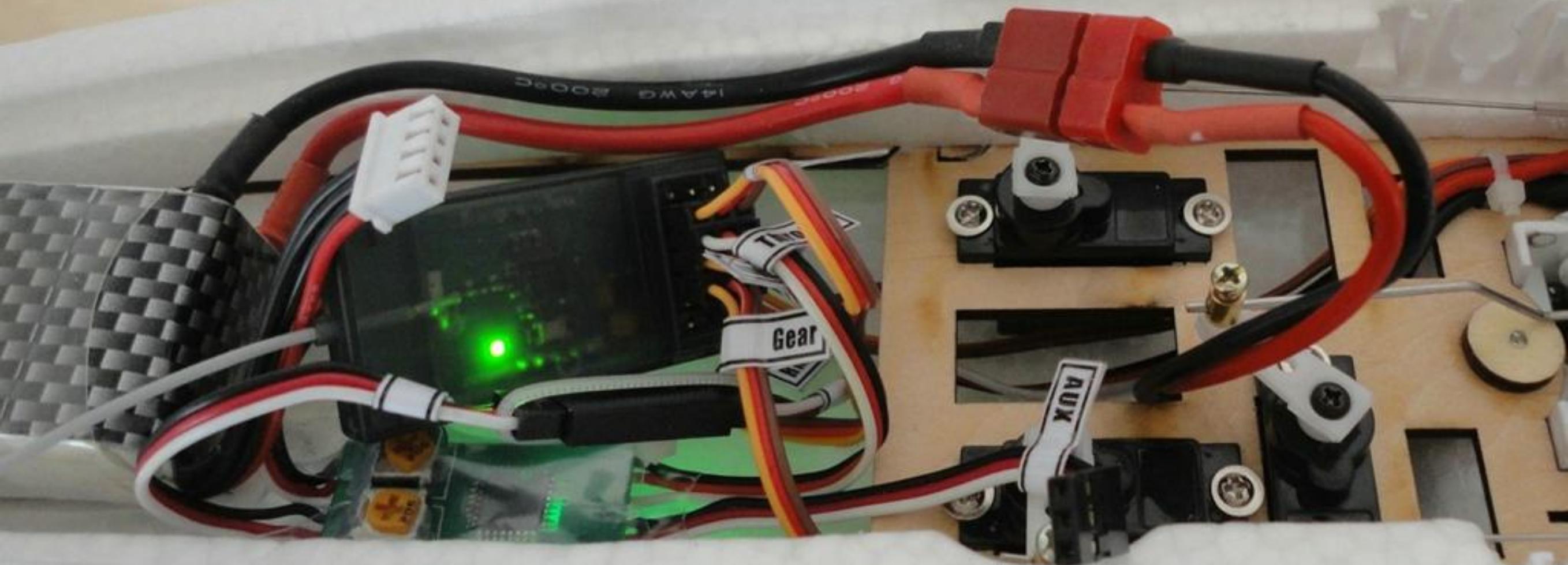
PIC. 16



Set the low end point adjusters of RMS servo in their mid position

**PIC. 17**

**Power the plane**

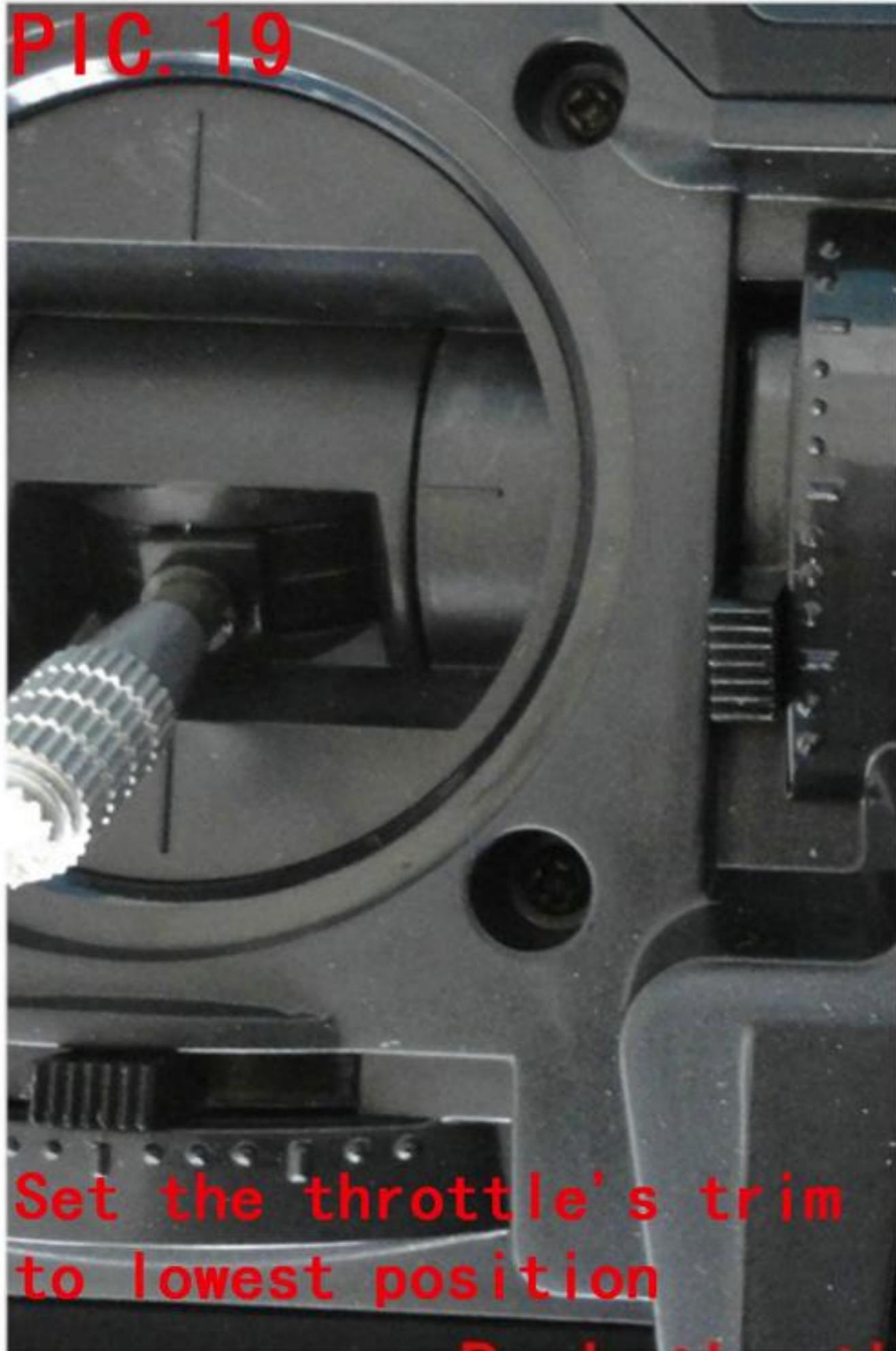


**PIC. 18**

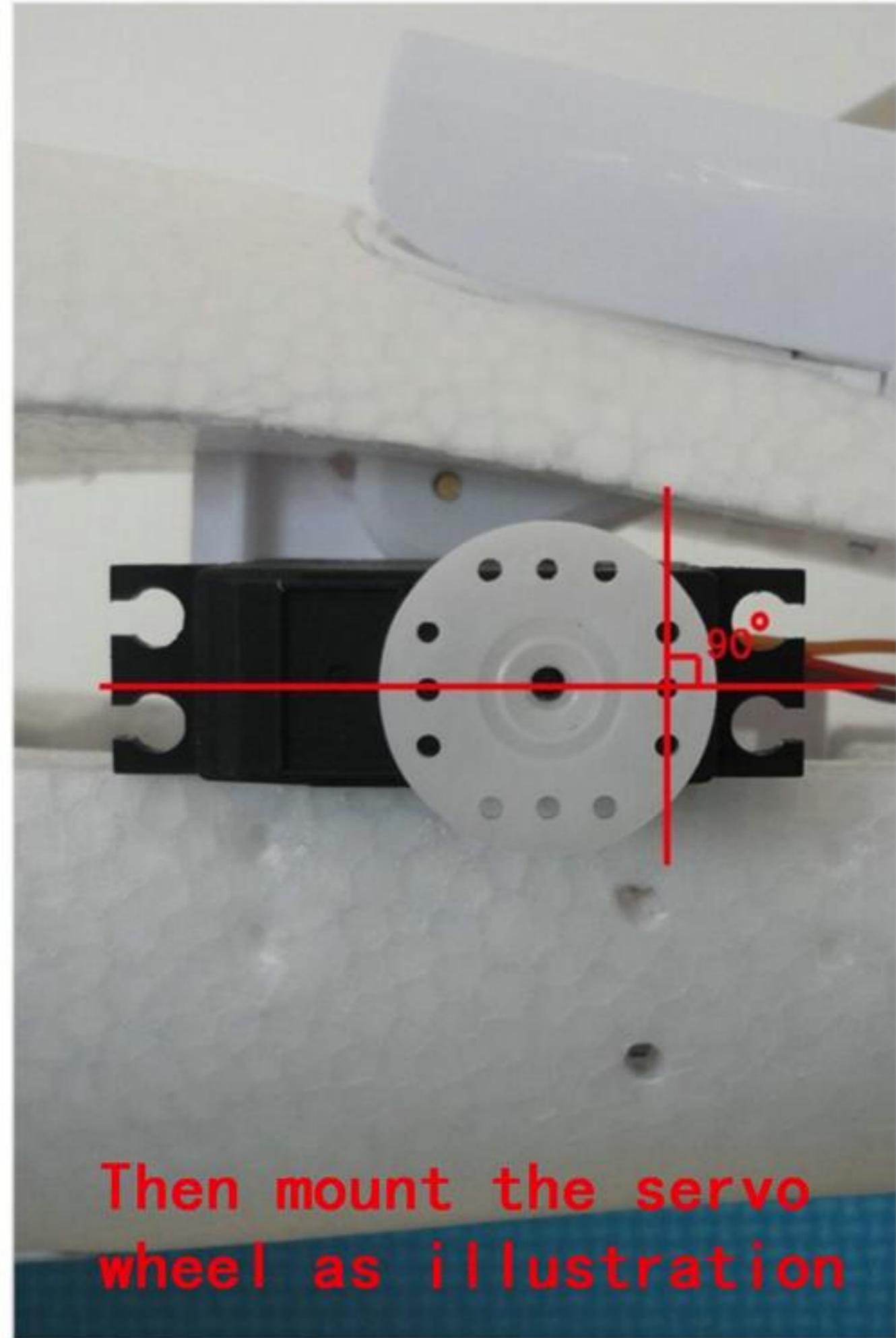


**Upward the throttle trim slowly, and the RMS servo will rotate anticlockwise**

PIC. 19



Set the throttle's trim to lowest position



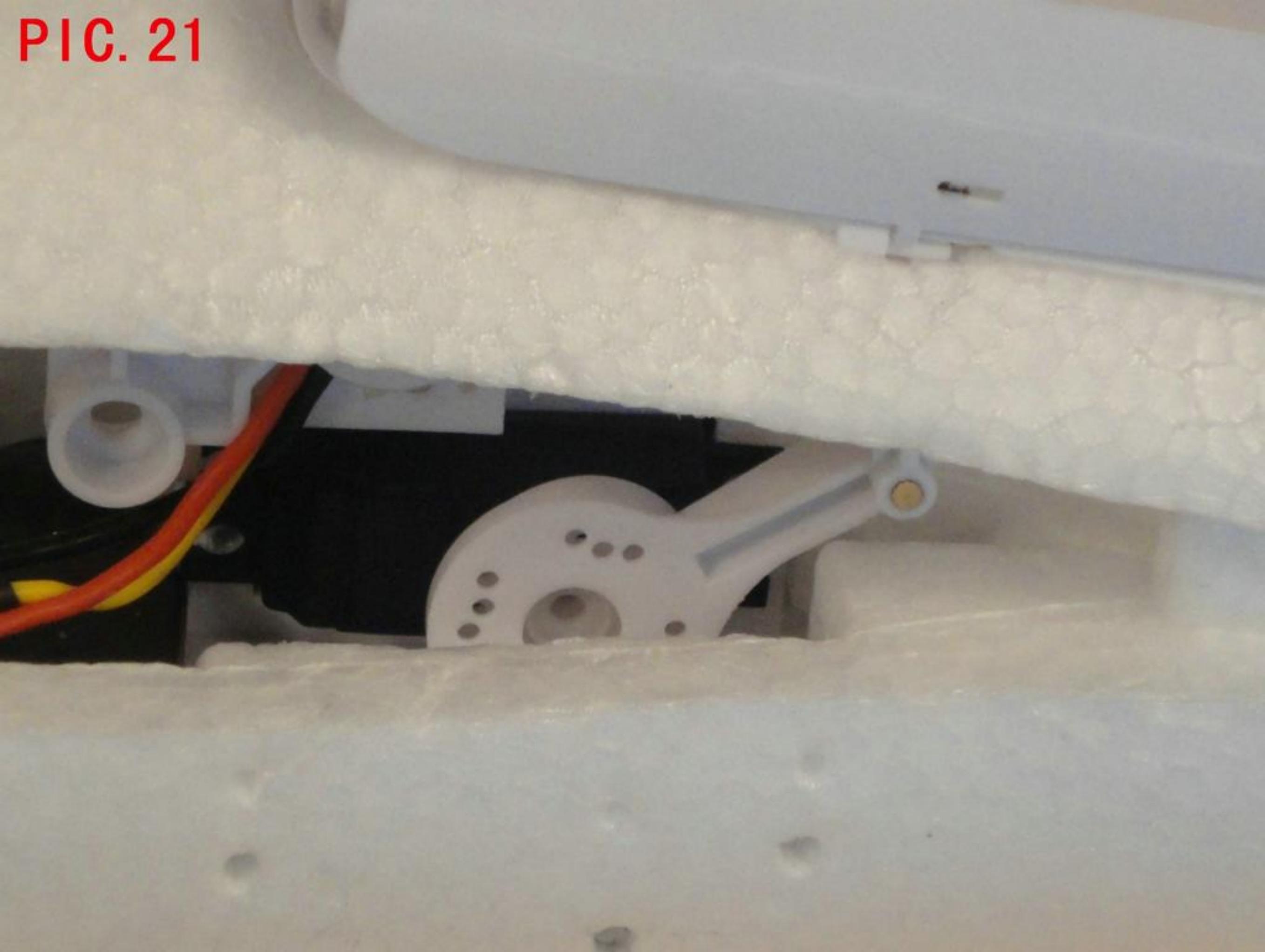
Then mount the servo wheel as illustration



**PIC. 20**

**Install the servo into the fuselage**

PIC. 21



**PIC. 22**



**Infix two tapping screws into the holes on the support, ensure the washer on the shaft not be lost**

PIC. 23



**PIC. 24**

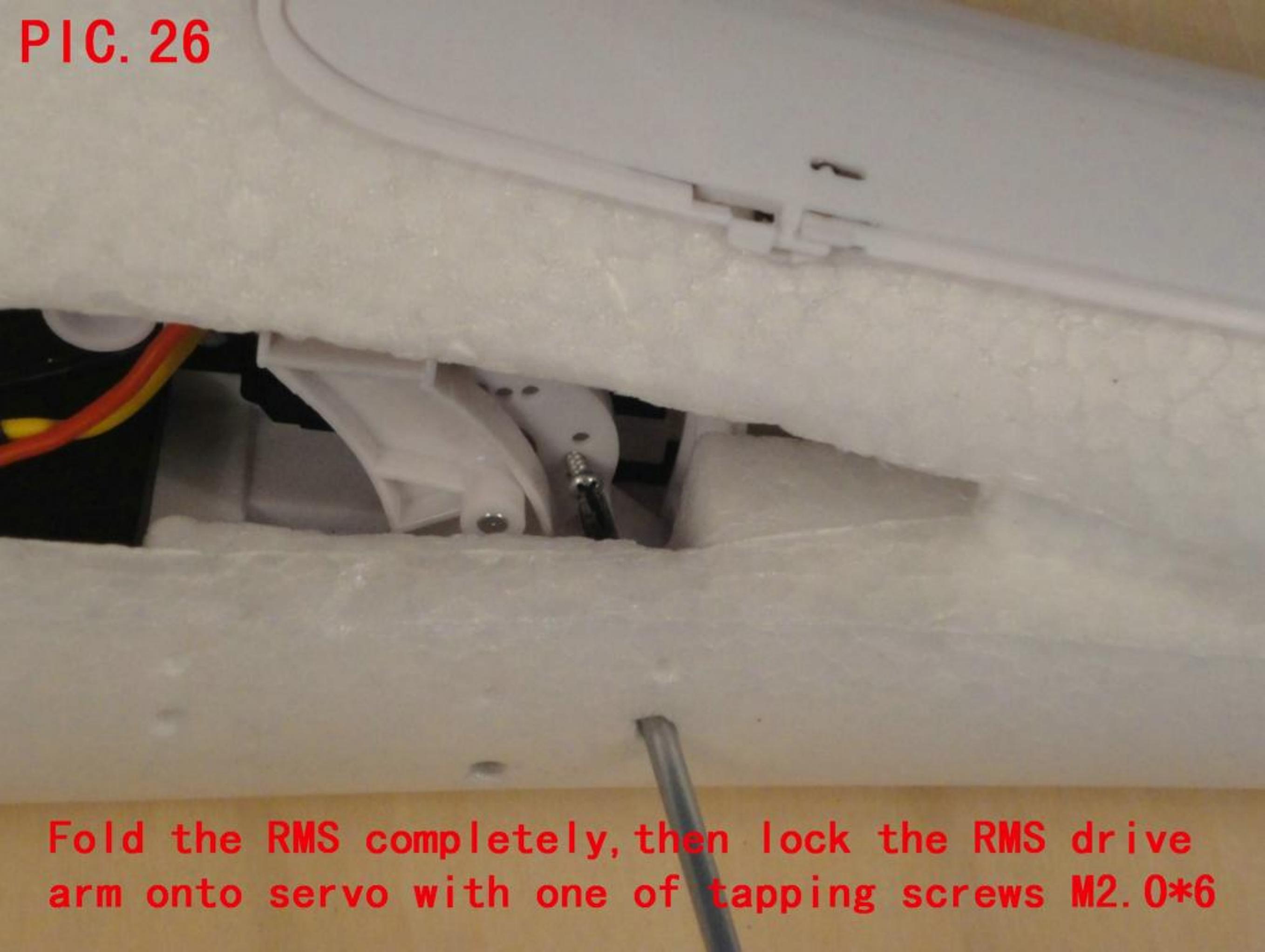


**Tighten the screws**

PIC. 25



**PIC. 26**



**Fold the RMS completely, then lock the RMS drive arm onto servo with one of tapping screws M2.0\*6**

PIC. 27



Upward the throttle trim until the RMS unfold, then lock the other M2.0\*6 tapping screw

**PIC. 28**

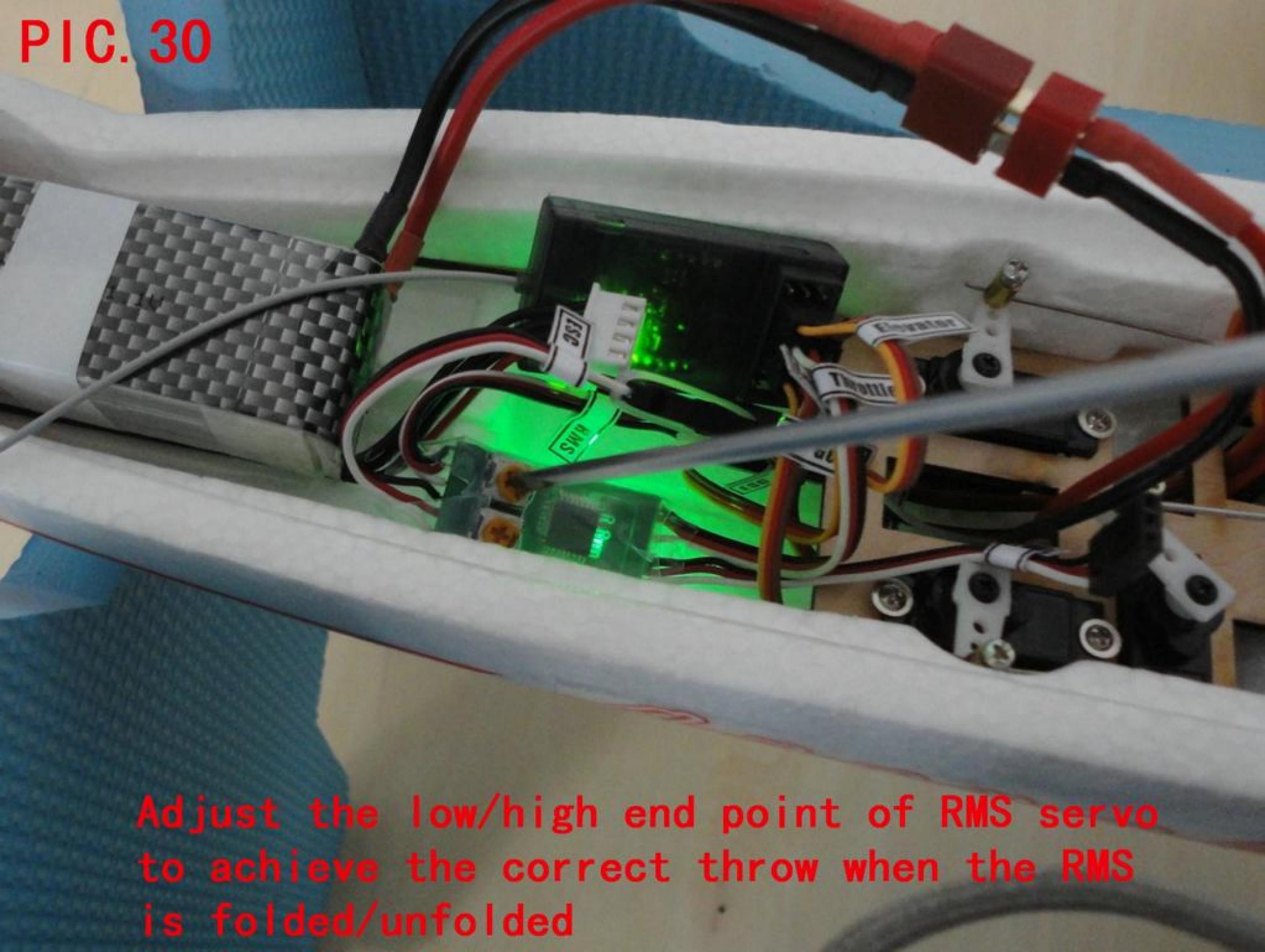


**Lock the servo into its position with screws**

PIC. 29



PIC. 30



Adjust the low/high end point of RMS servo to achieve the correct throw when the RMS is folded/unfolded